

```
1 #ifndef _SENSOR_DATA_H_
2 #define _SENSOR_DATA_H_
3
4 #include "stm32f4xx_hal.h"
5 #include "config_drone.h"
6 //#include "imu_6axes.h"
7 //#include "magneto.h"
8 //#include "pressure.h"
9 //#include "board.h"
10 #include "steval_fcu001_v1.h"
11
12 void ReadSensorRawData(void *ACC_handle, void *GYR_handle, void *MAG_handle, void
    *PRE_handle, AxesRaw_TypeDef *acc, AxesRaw_TypeDef *gyro, AxesRaw_TypeDef *mag, float
    *pre);
13
14
15 #endif /* _SENSOR_DATA_H_ */
```

座標軸の選択は config\_drone.h 内で行う。